# Extragradient algorithms for equilibrium problems and symmetric generalized hybrid mappings 

Bui Van Dinh ${ }^{1,2}$ • Do Sang Kim ${ }^{2}$

Received: 25 June 2015 / Accepted: 22 February 2016
© Springer-Verlag Berlin Heidelberg 2016


#### Abstract

In this paper, we propose new algorithms for finding a common point of the solution set of a pseudomonotone equilibrium problem and the set of fixed points of a symmetric generalized hybrid mapping in a real Hilbert space. The convergence of the iterates generated by each method is obtained under assumptions that the fixed point mapping is quasi-nonexpansive and demiclosed at 0 , and the bifunction associated with the equilibrium problem is weakly continuous. The bifunction is assumed to be satisfying a Lipschitz-type condition when the basic iteration comes from the extragradient method. It becomes unnecessary when an Armijo back tracking linesearch is incorporated in the extragradient method.


Keywords Equilibrium problem • Fixed point problem • Pseudo-monotonicity • Extragradient method Armijo linesearch • Strong convergence

## 1 Introduction

Let $\mathbb{H}$ be a real Hilbert space with the inner product $\langle\cdot, \cdot\rangle$ and induced norm $\|\cdot\|$. By ' $\rightarrow$ ' and ' $\rightharpoonup$ ' we denote the strong convergence and the weak convergence in $\mathbb{H}$, respectively. Let $C$ be a nonempty closed convex subset of $\mathbb{H}$ and $f: C \times C \rightarrow \mathbb{R}$ be a bifunction satisfying $f(x, x)=0$ for every $x \in C$. Such a bifunction is called

[^0]an equilibrium bifunction. The equilibrium problem, in the sense of Blum, Muu and Oettli $[4,19]$ [shortly $\operatorname{EP}(C, f)]$, is to find $x^{*} \in C$ such that
\[

$$
\begin{equation*}
f\left(x^{*}, y\right) \geq 0, \quad \forall y \in C . \tag{1}
\end{equation*}
$$

\]

By $\operatorname{Sol}(C, f)$, we denote the solution set of $\operatorname{EP}(C, f)$. Although problem $\operatorname{EP}(C, f)$ has a simple formulation, it includes, as special cases, many important problems in applied mathematics: variational inequality problem, optimization problem, fixed point problem, saddle point problem, Nash equilibrium problem in noncooperative game, and others; see, for example, $[3,4,19]$, and the references quoted therein.

Let us denote the set of fixed points of a mapping $T: C \rightarrow C$ by Fix $(T)$; that is, Fix $(T)=\{x \in C: T x=x\}$. Recall that $T$ is said to be nonexpansive if for all $x, y \in C,\|T x-T y\| \leq\|x-y\|$. If $\operatorname{Fix}(T)$ is nonempty and $\|T x-p\| \leq$ $\|x-p\|, \forall x \in C, p \in \operatorname{Fix}(T)$, then $T$ is called quasi-nonexpansive. It is well-known that $\operatorname{Fix}(T)$ is closed and convex when $T$ is quasi-nonexpansive [13].

A mapping $T$ is said to be pseudocontractive if for all $x, y \in C$ and $\tau>0$,

$$
\|x-y\| \leq\|(1+\tau)(x-y)-\tau(T x-T y)\| .
$$

To find a fixed point of a Lipschitzian pseudocontractive map, Ishikawa [12], in 1974, proposed to use the following iteration procedure

$$
\left\{\begin{array}{l}
x^{0} \in C  \tag{2}\\
y^{k}=\alpha_{k} x^{k}+\left(1-\alpha_{k}\right) T x^{k} \\
x^{k+1}=\beta_{k} x^{k}+\left(1-\beta_{k}\right) T y^{k}
\end{array}\right.
$$

where $0 \leq \alpha_{k} \leq \beta_{k} \leq 1$ for all $k$ and proved that if $\lim _{k \rightarrow \infty} \beta_{k}=1, \sum_{k=1}^{\infty}(1-$ $\left.\alpha_{k}\right)\left(1-\beta_{k}\right)=\infty$, then $\left\{x^{k}\right\}$ generated by (2) converges weakly to a fixed point of mapping $T$ (see $[10,12]$ ).

In 2006, Yanes and Xu [29] introduced the following by combining Ishikawa iteration process with hybrid projection method [20] for a nonexpansive mapping $T$.

$$
\left\{\begin{array}{l}
x^{0} \in C  \tag{3}\\
y^{k}=\alpha_{k} x^{k}+\left(1-\alpha_{k}\right) T x^{k} \\
z^{k}=\beta_{k} x^{k}+\left(1-\beta_{k}\right) T y^{k} \\
C_{k}=\left\{x \in C:\left\|x-z^{k}\right\|^{2} \leq\left\|x-x^{k}\right\|^{2}+\left(1-\alpha_{k}\right)\left(\left\|y^{k}\right\|^{2}-\left\|x^{k}\right\|^{2}+2\left\langle x^{k}-y^{k}, x\right\rangle\right)\right\} \\
Q_{k}=\left\{x \in C:\left\langle x-x^{k}, x^{0}-x^{k}\right\rangle \leq 0\right\} \\
x^{k+1}=P_{C_{k} \cap Q_{k}} x^{0},
\end{array}\right.
$$

where $\left\{\alpha_{k}\right\}$ and $\left\{\beta_{k}\right\}$ are sequences in $[0,1]$. They proved that if $\lim _{k \rightarrow \infty} \alpha_{k}=1$ and $\beta_{k} \leq \bar{\beta}$ for some $\bar{\beta} \in[0,1)$, then $\left\{x^{k}\right\}$ generated by (3) converges strongly to $P_{\text {Fix }(T)}\left(x^{0}\right)$.

In recent years, many researchers studied the problem of finding a common element of the set of solutions of an equilibrium problem and the set of fixed points
of a nonexpansive or demicontractive mapping; see, for instance, [2,5,17,21,28] and the references therein. Remember that a mapping $T: C \rightarrow \mathbb{H}$ is called symmetric generalized hybrid [11,14,25] if there exist $\alpha, \beta, \gamma, \delta \in \mathbb{R}$ such that

$$
\begin{aligned}
& \alpha\|T x-T y\|^{2}+\beta\left(\|x-T y\|^{2}+\|y-T x\|^{2}\right)+\gamma\|x-y\|^{2} \\
& \quad+\delta\left(\|x-T x\|^{2}+\|y-T y\|^{2}\right) \leq 0, \quad \forall x, y \in C .
\end{aligned}
$$

Such a mapping is called an $(\alpha, \beta, \gamma, \delta)$-symmetric generalized hybrid mapping.
For obtaining a common element of the set of solutions of $\operatorname{EP}(C, f)$ and fixed points of a symmetric generalized hybrid mapping $T$, Moradlou and Alizadeh [18] proposed to combine Ishikawa iterative scheme with the hybrid projection method [20,23,24]. More precisely, the iterates $x^{k}, y^{k}, u^{k}, z^{k}$ are calculated as follows:

$$
\left\{\begin{array}{l}
x^{0} \in C  \tag{4}\\
u^{k} \in C \text { such that } f\left(u^{k}, y\right)+\frac{1}{r_{k}}\left\langle y-u^{k}, u^{k}-x^{k}\right\rangle \geq 0, \quad \forall y \in C \\
y^{k}=\alpha_{k} x^{k}+\left(1-\alpha_{k}\right) T x^{k}, \\
z^{k}=\beta_{k} y^{k}+\left(1-\beta_{k}\right) T u^{k} \\
C_{k}=\left\{x \in C:\left\|x-z^{k}\right\| \leq\left\|x-x^{k}\right\|\right\} \\
Q_{k}=\left\{x \in C:\left\langle x-x^{k}, x^{0}-x^{k}\right\rangle \leq 0\right\} \\
x^{k+1}=P_{C_{k} \cap Q_{k}} x^{0} .
\end{array}\right.
$$

The authors showed that if $\operatorname{Sol}(C, f) \cap \operatorname{Fix}(T) \neq \emptyset,(\alpha, \beta, \gamma, \delta)$-symmetric generalized hybrid mapping $T$ satisfying (1) $\alpha+2 \beta+\gamma \geq 0$, (2) $\alpha+\beta>0$, and (3) $\delta \geq 0$, then under certain appropriate conditions imposed on $\left\{\alpha_{k}\right\}$, $\left\{\beta_{k}\right\}$, the sequence $\left\{x^{k}\right\}$ converges strongly to $x^{*}=P_{S o l(C, f) \cap F i x(T)}\left(x^{0}\right)$ provided that $f$ is monotone on $C$. Note that mapping $T$ satisfies the conditions (1)-(3), then $T$ is quasi-nonexpansive and demiclosed at 0 .

In this paper, we modify Moradlou and Alizadeh's iteration process for finding a common element of the set of solutions of an equilibrium problem and the set of fixed points of a generalized hybrid mapping in a real Hilbert space in which the bifunction $f$ is pseudomonotone on $C$ with respect to $\operatorname{Sol}(C, f)$. More precisely, we propose to use the extragradient algorithm [16] for solving the equilibrium problem (see also [7-9, 15,26] for more detail extragradient algorithms). One advantage of our algorithm is that it could be applied for the pseudomonotone equilibrium problem case and each iteration we only have to solve two strongly convex optimization problems instead of a regularized equilibrium as in Moradou and Alizaded's method.

The paper is organized as follows. The next section contains some preliminaries on the metric projection, equilibrium problems and symmetric generalized hybrid mappings. An extragradient algorithm and its convergence is presented in the third section. The last section is devoted to presentation of an extragradient algorithm with linesearch and its convergence.

## 2 Preliminaries

In the rest of this paper, by $P_{C}$ we denote the metric projection operator on $C$, that is

$$
P_{C}(x) \in C:\left\|x-P_{C}(x)\right\| \leq\|y-x\|, \quad \forall y \in C .
$$

The following well known results on the projection operator onto a closed convex set will be used in the sequel.

Lemma 1 Suppose that $C$ is a nonempty closed convex subset in $\mathbb{H}$. Then
(a) $P_{C}(x)$ is singleton and well defined for every $x$;
(b) $z=P_{C}(x)$ if and only if $\langle x-z, y-z\rangle \leq 0, \forall y \in C$;
(c) $\left\|P_{C}(x)-P_{C}(y)\right\|^{2} \leq\|x-y\|^{2}-\left\|P_{C}(x)-x+y-P_{C}(y)\right\|^{2}, \forall x, y \in C$.

Lemma 2 [29] Let C be a nonempty closed convex subset of $\mathbb{H}$. Let $\left\{x^{k}\right\}$ be a sequence in $\mathbb{H}$ and $u \in \mathbb{H}$. If any weak limit point of $\left\{x^{k}\right\}$ belongs to $C$ and

$$
\left\|x^{k}-u\right\| \leq\left\|u-P_{C}(u)\right\|, \quad \forall k
$$

Then $x^{k} \rightarrow P_{C}(u)$.
Definition 1 A bifunction $\varphi: C \times C \rightarrow \mathbb{R}$ is said to be jointly weakly continuous on $C \times C$ if for all $x, y \in C$ and $\left\{x^{k}\right\},\left\{y^{k}\right\}$ are two sequences in $C$ converging weakly to $x$ and $y$ respectively, then $\varphi\left(x^{k}, y^{k}\right)$ converges to $\varphi(x, y)$.

In the sequel, we need the following blanket assumptions
$\left(A_{1}\right) f$ is jointly weakly continuous on $C \times C$;
$\left(A_{2}\right) f(x, \cdot)$ is convex, lower semicontinuous, and subdifferentiable on $C$, for all $x \in C$;
$\left(A_{3}\right) f$ is pseudomonotone on $C$ with respect to $\operatorname{Sol}(C, f)$, i.e., $f\left(x, x^{*}\right) \leq 0$ for all $x \in C, x^{*} \in \operatorname{Sol}(C, f)$;
$\left(A_{4}\right) f$ is Lipschitz-type continuous on $C$ with constants $L_{1}>0$ and $L_{2}>0$, i.e.,

$$
f(x, y)+f(y, z) \geq f(x, z)-L_{1}\|x-y\|^{2}-L_{2}\|y-z\|^{2}, \quad \forall x, y, z \in C
$$

( $A_{5}$ ) $T$ is an $(\alpha, \beta, \gamma, \delta)$-symmetric generalized hybrid self-mapping of $C$ such that (1) $\alpha+2 \beta+\gamma \geq 0$, (2) $\alpha+\beta>0$, (3) $\delta \geq 0$, and Fix (T) is nonempty.
For each $z, x \in C$, by $\partial_{2} f(z, x)$ we denote the subdifferential of the convex function $f(z,$.$) at x$, i.e.,

$$
\partial_{2} f(z, x):=\{w \in \mathbb{H}: f(z, y) \geq f(z, x)+\langle w, y-x\rangle, \quad \forall y \in C\} .
$$

In particular,

$$
\partial_{2} f(z, z)=\{w \in \mathbb{H}: f(z, y) \geq\langle w, y-z\rangle, \quad \forall y \in C\} .
$$

Let $\Omega$ be an open convex set containing $C$. The next lemma can be considered as an infinite-dimensional version of Theorem 24.5 in [22].

Lemma 3 [27, Proposition 4.3] Let $f: \Omega \times \Omega \rightarrow \mathbb{R}$ be a function satisfying conditions $\left(A_{1}\right)$ on $\Omega$ and $\left(A_{2}\right)$ on $C$. Let $\bar{x}, \bar{y} \in \Omega$ and $\left\{x^{k}\right\},\left\{y^{k}\right\}$ be two sequences in $\Omega$ converging weakly to $\bar{x}, \bar{y}$, respectively. Then, for any $\epsilon>0$, there exist $\eta>0$ and $k_{\epsilon} \in \mathbb{N}$ such that

$$
\partial_{2} f\left(x^{k}, y^{k}\right) \subset \partial_{2} f(\bar{x}, \bar{y})+\frac{\epsilon}{\eta} B
$$

for every $k \geq k_{\epsilon}$, where $B$ denotes the closed unit ball in $\mathbb{H}$.
Lemma 4 Suppose the bifunction $f$ satisfies the assumptions $\left(A_{1}\right)$ on $\Omega$ and $\left(A_{2}\right)$ on C. If $\left\{x^{k}\right\} \subset C$ is bounded, $\rho>0$, and $\left\{y^{k}\right\}$ is a sequence such that

$$
y^{k}=\arg \min \left\{f\left(x^{k}, y\right)+\frac{\rho}{2}\left\|y-x^{k}\right\|^{2}: y \in C\right\}
$$

then $\left\{y^{k}\right\}$ is bounded.
Proof Firstly, we show that if $\left\{x^{k}\right\}$ converges weakly to $x^{*}$, then $\left\{y^{k}\right\}$ is bounded. Indeed,

$$
y^{k}=\arg \min \left\{f\left(x^{k}, y\right)+\frac{\rho}{2}\left\|y-x^{k}\right\|^{2}: y \in C\right\},
$$

and

$$
f\left(x^{k}, x^{k}\right)+\frac{\rho}{2}\left\|x^{k}-x^{k}\right\|^{2}=0
$$

therefore

$$
f\left(x^{k}, y^{k}\right)+\frac{\rho}{2}\left\|y^{k}-x^{k}\right\|^{2} \leq 0, \quad \forall k
$$

In addition, for all $w^{k} \in \partial_{2} f\left(x^{k}, x^{k}\right)$ we have

$$
f\left(x^{k}, y^{k}\right)+\frac{\rho}{2}\left\|y^{k}-x^{k}\right\|^{2} \geq\left\langle w^{k}, y^{k}-x^{k}\right\rangle+\frac{\rho}{2}\left\|y^{k}-x^{k}\right\|^{2} .
$$

This implies $-\left\|w^{k}\right\|\left\|y^{k}-x^{k}\right\|+\frac{\rho}{2}\left\|y^{k}-x^{k}\right\|^{2} \leq 0$. Hence,

$$
\left\|y^{k}-x^{k}\right\| \leq \frac{2}{\rho}\left\|w^{k}\right\|, \quad \forall k
$$

Because $\left\{x^{k}\right\}$ converges weakly to $x^{*}$ and $w^{k} \in \partial_{2} f\left(x^{k}, x^{k}\right)$, by Lemma 3, the sequence $\left\{w^{k}\right\}$ is bounded, combining with the boundedness of $\left\{x^{k}\right\}$, we get $\left\{y^{k}\right\}$ is also bounded.

Now we prove the Lemma 4. Suppose that $\left\{y^{k}\right\}$ is unbounded, i.e., there exists an subsequence $\left\{y^{k_{i}}\right\} \subseteq\left\{y^{k}\right\}$ such that $\lim _{i \rightarrow \infty}\left\|y^{k_{i}}\right\|=+\infty$. By the boundedness of $\left\{x^{k}\right\}$, it implies $\left\{x^{k_{i}}\right\}$ is also bounded, without loss of generality, we may assume that
$\left\{x^{k_{i}}\right\}$ converges weakly to some $x^{*}$. By the same argument as above, we obtain $\left\{y^{k_{i}}\right\}$ is bounded, which contradicts. Therefore $\left\{y^{k}\right\}$ is bounded.

Lemma 5 [14] Let $C$ be a nonempty closed convex subset of $\mathbb{H}$. Assume that $T$ is an $(\alpha, \beta, \gamma, \delta)$-symmetric generalized hybrid self-mapping of $C$ such that Fix $(T) \neq \emptyset$ and the conditions (1) $\alpha+2 \beta+\gamma \geq 0$, (2) $\alpha+\beta>0$ and (3) $\delta \geq 0$ hold. Then $T$ is quasi-nonexpansive.

Lemma 6 [11] Let $C$ be a nonempty closed convex subset of $\mathbb{H}$. Assume that $T$ is an $(\alpha, \beta, \gamma, \delta)$-symmetric generalized hybrid self-mapping of C such that Fix $(T) \neq \emptyset$ and the conditions (1) $\alpha+2 \beta+\gamma \geq 0$, (2) $\alpha+\beta>0$ and (3) $\delta \geq 0$ hold. Then $I-T$ is demiclosed at 0 , i.e., $x^{k} \rightharpoonup \bar{x}$ and $x^{k}-T x^{k} \rightarrow 0$ imply $\bar{x} \in \operatorname{Fix}(T)$.

## 3 An extragradient algorithm

## Algorithm 1

Initialization. Pick $x^{0}=x^{g} \in C$, choose parameters $\left\{\rho_{k}\right\} \subset[\rho, \bar{\rho}]$, with $0<$ $\underline{\rho} \leq \bar{\rho}<\min \left\{\frac{1}{2 L_{1}}, \frac{1}{2 L_{2}}\right\},\left\{\alpha_{k}\right\} \subset[0,1], \lim _{k \rightarrow \infty} \alpha_{k}=1,\left\{\beta_{k}\right\} \subset[0, \bar{\beta}] \subset[0,1)$. Iteration $k(k=0,1,2, \ldots)$. Having $x^{k}$ do the following steps:

Step 1 . Solve the successively strongly convex programs

$$
\begin{array}{ll}
\min \left\{\rho_{k} f\left(x^{k}, y\right)+\frac{1}{2}\left\|y-x^{k}\right\|^{2}: y \in C\right\} & C P\left(x^{k}\right) \\
\min \left\{\rho_{k} f\left(y^{k}, y\right)+\frac{1}{2}\left\|y-x^{k}\right\|^{2}: y \in C\right\} & C P\left(y^{k}, x^{k}\right)
\end{array}
$$

to obtain their unique solutions $y^{k}$ and $z^{k}$ respectively.
Step 2. Compute

$$
\begin{aligned}
t^{k} & =\alpha_{k} x^{k}+\left(1-\alpha_{k}\right) T x^{k} \\
u^{k} & =\beta_{k} t^{k}+\left(1-\beta_{k}\right) T z^{k}
\end{aligned}
$$

Step 3. Define

$$
\begin{aligned}
C_{k} & =\left\{x \in \mathbb{H}:\left\|x-u^{k}\right\| \leq\left\|x-x^{k}\right\|\right\}, \\
Q_{k} & =\left\{x \in \mathbb{H}:\left\langle x-x^{k}, x^{g}-x^{k}\right\rangle \leq 0\right\}, \\
A_{k} & =C_{k} \cap Q_{k} \cap C .
\end{aligned}
$$

Take $x^{k+1}=P_{A_{k}}\left(x^{g}\right)$, and go to Step 1 with $k$ is replaced by $k+1$.
Before going to prove the convergence of this algorithm, let us recall the following result which was proved in [1]

Lemma 7 [1] Suppose that $x^{*} \in \operatorname{Sol}(C, f)$, then under assumptions $\left(A_{2}\right),\left(A_{3}\right)$, and $\left(A_{4}\right)$, we have:
(i) $\rho_{k}\left[f\left(x^{k}, y\right)-f\left(x^{k}, y^{k}\right)\right] \geq\left\langle y^{k}-x^{k}, y^{k}-y\right\rangle, \forall y \in C$.
(ii) $\left\|z^{k}-x^{*}\right\|^{2} \leq\left\|x^{k}-x^{*}\right\|^{2}-\left(1-2 \rho_{k} L_{1}\right)\left\|x^{k}-y^{k}\right\|^{2}-\left(1-2 \rho_{k} L_{2}\right)\left\|y^{k}-z^{k}\right\|^{2}, \quad \forall k$.

Theorem 1 Suppose that the set $S=\operatorname{Sol}(C, f) \cap \operatorname{Fix}(T)$ is nonempty. Then under assumptions $\left(A_{1}\right),\left(A_{2}\right),\left(A_{3}\right),\left(A_{4}\right)$, and $\left(A_{5}\right)$ the sequences $\left\{x^{k}\right\},\left\{y^{k}\right\},\left\{z^{k}\right\}$ generated by Algorithm 1 converge strongly to the solution $x^{*}=P_{S}\left(x^{g}\right)$.
Proof Take $q \in S$, i.e., $q \in \operatorname{Sol}(C, f) \cap \operatorname{Fix}(T)$. By definition of $\rho_{k}: 0<\underline{\rho} \leq \rho_{k} \leq$ $\bar{\rho}<\min \left\{\frac{1}{2 L_{1}}, \frac{1}{2 L_{2}}\right\}$, we get from Lemma 7 that

$$
\begin{equation*}
\left\|z^{k}-q\right\| \leq\left\|x^{k}-q\right\| \tag{5}
\end{equation*}
$$

By definition of $t^{k}$, we have

$$
\begin{aligned}
\left\|t^{k}-q\right\| & =\left\|\alpha_{k} x^{k}+\left(1-\alpha_{k}\right) T x^{k}-q\right\| \\
& \leq \alpha_{k}\left\|x^{k}-q\right\|+\left(1-\alpha_{k}\right)\left\|T x^{k}-q\right\| .
\end{aligned}
$$

Since $T$ is $(\alpha, \beta, \gamma, \delta)$-symmetric generalized hybrid mapping with $\alpha+2 \beta+\gamma \geq 0$, $\alpha+\beta>0, \delta \geq 0$. From Lemma 5 it is quasi-nonexpansive, so

$$
\begin{equation*}
\left\|t^{k}-q\right\| \leq\left\|x^{k}-q\right\| \tag{6}
\end{equation*}
$$

Similarly

$$
\begin{aligned}
\left\|u^{k}-q\right\| & =\left\|\beta_{k} t^{k}+\left(1-\beta_{k}\right) T z^{k}-q\right\| \\
& \leq \beta_{k}\left\|t^{k}-q\right\|+\left(1-\beta_{k}\right)\left\|T z^{k}-q\right\| \\
& \leq \beta_{k}\left\|x^{k}-q\right\|+\left(1-\beta_{k}\right)\left\|z^{k}-q\right\| .
\end{aligned}
$$

Combining with (5) yields

$$
\begin{equation*}
\left\|u^{k}-q\right\| \leq\left\|x^{k}-q\right\| . \tag{7}
\end{equation*}
$$

Next, we show that $S \subset C_{k} \cap Q_{k}, \forall k$. Indeed, from (7) it implies that $q \in C_{k}$, or $S \subset C_{k}$ for all $k$. We prove $S \subset Q_{k}$ by induction. It is clear that $S \subset Q_{0}$. If $S \subset Q_{k}$, i.e., $\left\langle q-x^{k}, x^{g}-x^{k}\right\rangle \leq 0, \forall q \in S$. Since $x^{k+1}=P_{A_{k}}\left(x^{g}\right)$ we obtain $\left\langle x-x^{k+1}, x^{g}-x^{k+1}\right\rangle \leq 0, \forall x \in A_{k}$. Especially, $\left\langle q-x^{k+1}, x^{g}-x^{k+1}\right\rangle \leq 0, \forall q \in S$. So $S \subset C_{k} \cap Q_{k}, \forall k$.
From definition of $Q_{k}$, it implies that $x^{k}=P_{Q_{k}}\left(x^{g}\right)$, so $\left\|x^{k}-x^{g}\right\| \leq\left\|x-x^{g}\right\|, \forall x \in$ $Q_{k}$. In particular

$$
\begin{equation*}
\left\|x^{k}-x^{g}\right\| \leq\left\|q-x^{g}\right\|, \quad \forall k, \quad \forall q \in S \tag{8}
\end{equation*}
$$

Consequently, $\left\{x^{k}\right\}$ is bounded. Combining with (6) and (7), we get $\left\{t^{k}\right\},\left\{u^{k}\right\}$ are also bounded.
In addition,

$$
\begin{aligned}
\left\|x^{k+1}-x^{k}\right\|^{2} & =\left\|x^{k+1}-x^{g}+x^{g}-x^{k}\right\|^{2} \\
& =\left\|x^{k+1}-x^{g}\right\|^{2}+\left\|x^{g}-x^{k}\right\|^{2}+2\left\langle x^{k+1}-x^{g}, x^{g}-x^{k}\right\rangle \\
& =\left\|x^{k+1}-x^{g}\right\|^{2}-\left\|x^{g}-x^{k}\right\|^{2}+2\left\langle x^{k+1}-x^{k}, x^{g}-x^{k}\right\rangle .
\end{aligned}
$$

Since $x^{k+1} \in Q_{k}$, it implies from the above inequality that

$$
\begin{equation*}
\left\|x^{k+1}-x^{k}\right\|^{2} \leq\left\|x^{k+1}-x^{g}\right\|^{2}-\left\|x^{k}-x^{g}\right\|^{2} \tag{9}
\end{equation*}
$$

Therefore $\left\{\left\|x^{k}-x^{g}\right\|\right\}$ is nondecreasing sequence. In view of (8), the limit $\lim _{k \rightarrow \infty}\left\|x^{k}-x^{g}\right\|$ exists. Hence, it also follows from (9) that

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|x^{k+1}-x^{k}\right\|=0 \tag{10}
\end{equation*}
$$

Because $x^{k+1} \in C_{k}$, it implies that

$$
\begin{aligned}
\left\|u^{k}-x^{k}\right\| & \leq\left\|u^{k}-x^{k+1}\right\|+\left\|x^{k+1}-x^{k}\right\| \\
& \leq 2\left\|x^{k+1}-x^{k}\right\|
\end{aligned}
$$

therefore, we deduce from (10) that

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|u^{k}-x^{k}\right\|=0 \tag{11}
\end{equation*}
$$

Besides that $\lim _{k \rightarrow \infty} \alpha_{k}=1$, so

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|t^{k}-x^{k}\right\|=\lim _{k \rightarrow \infty}\left(1-\alpha_{k}\right)\left\|x^{k}-T x^{k}\right\|=0 \tag{12}
\end{equation*}
$$

It is clear that

$$
\begin{aligned}
\left\|u^{k}-q\right\|^{2} & =\left\|\beta_{k}\left(t^{k}-q\right)+\left(1-\beta_{k}\right)\left(T z^{k}-q\right)\right\|^{2} \\
& =\beta_{k}\left\|t^{k}-q\right\|^{2}+\left(1-\beta_{k}\right)\left\|T z^{k}-q\right\|^{2}-\beta_{k}\left(1-\beta_{k}\right)\left\|t^{k}-T z^{k}\right\|^{2} \\
& \leq \beta_{k}\left\|t^{k}-q\right\|^{2}+\left(1-\beta_{k}\right)\left\|T z^{k}-q\right\|^{2} .
\end{aligned}
$$

In view of (6), Lemmas 5 and 7, yields

$$
\begin{aligned}
\left\|u^{k}-q\right\|^{2} \leq & \left\|x^{k}-q\right\|^{2}-\left(1-\beta_{k}\right)\left[\left(1-2 \rho_{k} L_{1}\right)\left\|x^{k}-y^{k}\right\|^{2}\right. \\
& \left.-\left(1-2 \rho_{k} L_{2}\right)\left\|y^{k}-z^{k}\right\|^{2}\right] .
\end{aligned}
$$

Hence

$$
\begin{align*}
& \left(1-\beta_{k}\right)\left[\left(1-2 \rho_{k} L_{1}\right)\left\|x^{k}-y^{k}\right\|^{2}+\left(1-2 \rho_{k} L_{2}\right)\left\|y^{k}-z^{k}\right\|^{2}\right] \\
& \quad \leq\left\|x^{k}-u^{k}\right\|\left[\left\|x^{k}-q\right\|+\left\|u^{k}-q\right\|\right] \tag{13}
\end{align*}
$$

Since $0<1-\bar{\beta} \leq 1-\beta_{k} ; 0<\underline{\rho} \leq \rho_{k} \leq \bar{\rho}<\min \left\{\frac{1}{2 L_{1}}, \frac{1}{2 L_{2}}\right\}$, and (11), we get from (13) that

$$
\begin{align*}
\lim _{k \rightarrow \infty}\left\|x^{k}-y^{k}\right\| & =0  \tag{14}\\
\lim _{k \rightarrow \infty}\left\|y^{k}-z^{k}\right\| & =0  \tag{15}\\
\lim _{k \rightarrow \infty}\left\|x^{k}-z^{k}\right\| & =0 \tag{16}
\end{align*}
$$

By definition of $u^{k}$, we have $\left(1-\beta_{k}\right) T z^{k}=u^{k}-\beta_{k} t^{k}$. Hence

$$
\begin{aligned}
(1-\bar{\beta})\left\|T z^{k}-z^{k}\right\| & \leq\left\|\left(1-\beta_{k}\right) T z^{k}-\left(1-\beta_{k}\right) z^{k}\right\| \\
& =\left\|u^{k}-z^{k}-\beta_{k}\left(t^{k}-z^{k}\right)\right\| \\
& \leq\left\|u^{k}-z^{k}\right\|+\beta_{k}\left\|t^{k}-z^{k}\right\| \\
& \leq\left\|u^{k}-x^{k}\right\|+\beta_{k}\left\|t^{k}-x^{k}\right\|+\left(1+\beta_{k}\right)\left\|x^{k}-z^{k}\right\| .
\end{aligned}
$$

Combining this fact with (11), (12), and (16) we receive in the limit that

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|T z^{k}-z^{k}\right\|=0 \tag{17}
\end{equation*}
$$

Next we show that any weak accumulation point of $\left\{x^{k}\right\}$ belongs to $S$. Indeed, suppose that $\left\{x^{k_{i}}\right\} \subset\left\{x^{k}\right\}$ and $x^{k_{i}} \rightharpoonup p$ as $i \rightarrow \infty$. From (14), (15), and (16) we get $y^{k_{i}} \rightharpoonup p$, and $z^{k_{i}} \rightharpoonup p$ as $i \rightarrow \infty$. Replacing $k$ by $k_{i}$ in assertion (i) of Lemma 7 we get

$$
\rho_{k_{i}}\left[f\left(x^{k_{i}}, y\right)-f\left(x^{k_{i}}, y^{k_{i}}\right)\right] \geq\left\langle x^{k_{i}}-y^{k_{i}}, y-y^{k_{i}}\right\rangle, \quad \forall y \in C .
$$

Hence

$$
\begin{equation*}
\rho_{k_{i}}\left[f\left(x^{k_{i}}, y\right)-f\left(x^{k_{i}}, y^{k_{i}}\right)\right] \geq-\left\|x^{k_{i}}-y^{k_{i}}\right\|\left\|y-y^{k_{i}}\right\| . \tag{18}
\end{equation*}
$$

Letting $i \rightarrow \infty$, by jointly weak continuity of $f$ and (14), we obtain in the limit from (18) that

$$
f(p, y)-f(p, p) \geq 0
$$

So

$$
f(p, y) \geq 0, \quad \forall y \in C
$$

which means that $p$ is a solution of $\operatorname{EP}(C, f)$.
By (17), we have that $\lim _{i \rightarrow \infty}\left\|T z^{k_{i}}-z^{k_{i}}\right\|=0$. Since $z^{k_{i}} \rightharpoonup p$ and demiclosedness at zero of $I-T$, Lemma 6 , we get $T p=p$, i.e., $p \in \operatorname{Fix}(T)$.
Hence $p \in S$.
Now, we set $x^{*}=P_{S}\left(x^{g}\right)$. From (8) one has,

$$
\left\|x^{k}-x^{g}\right\| \leq\left\|x^{*}-x^{g}\right\|, \quad \forall k
$$

It is immediate from Lemma 2 that $x^{k}$ converges strongly to $x^{*}$. Combining with (14) and (16) we have that $y^{k}, z^{k}$ converge strongly to $x^{*}$. This completes the proof.

## 4 An extragradient algorithm with linesearch

## Algorithm 2

Initialization. Pick $x^{0}=x^{g} \in C$, choose parameters $\eta, \mu \in(0,1) ; 0<\underline{\rho} \leq \bar{\rho}$, $\left\{\rho_{k}\right\} \subset[\underline{\rho}, \bar{\rho}] ;$
$\left\{\alpha_{k}\right\} \subset[\overline{0}, 1], \lim _{k \rightarrow \infty} \alpha_{k}=1 ;\left\{\beta_{k}\right\} \subset[0, \bar{\beta}] \subset[0,1) ; \gamma_{k} \in[\underline{\gamma}, \bar{\gamma}] \subset(0,2)$.
Iteration $k(k=0,1,2, \ldots)$. Having $x^{k}$ do the following steps:
Step 1. Solve the strongly convex program

$$
\min \left\{\rho_{k} f\left(x^{k}, y\right)+\frac{1}{2}\left\|y-x^{k}\right\|^{2}: y \in C\right\} \quad C P\left(x^{k}\right)
$$

to obtain its unique solutions $y^{k}$.
If $y^{k}=x^{k}$, then set $v^{k}=x^{k}$. Otherwise go to Step 2 .
Step 2. (Armijo linesearch rule) Find $m_{k}$ as the smallest positive integer number $m$ such that

$$
\left\{\begin{array}{l}
z^{k, m}=\left(1-\eta^{m}\right) x^{k}+\eta^{m} y^{m}  \tag{19}\\
f\left(z^{k, m}, x^{k}\right)-f\left(z^{k, m}, y^{k}\right) \geq \frac{\mu}{2 \rho_{k}}\left\|x^{k}-y^{k}\right\|^{2}
\end{array}\right.
$$

Set $\eta_{k}=\eta^{m_{k}}, z^{k}=z^{k, m_{k}}$.
Step 3. Select $w^{k} \in \partial_{2} f\left(z^{k}, x^{k}\right)$, and compute $v^{k}=P_{C}\left(x^{k}-\gamma_{k} \cdot \sigma_{k} \cdot w^{k}\right)$, where $\sigma_{k}=\frac{f\left(z^{k}, x^{k}\right)}{\left\|w^{k}\right\|^{2}}$.
Step 4. Compute

$$
\begin{aligned}
t^{k} & =\alpha_{k} x^{k}+\left(1-\alpha_{k}\right) T x^{k} \\
u^{k} & =\beta_{k} t^{k}+\left(1-\beta_{k}\right) T v^{k}
\end{aligned}
$$

Step 5. Define

$$
\begin{aligned}
C_{k} & =\left\{x \in \mathbb{H}:\left\|x-u^{k}\right\| \leq\left\|x-x^{k}\right\|\right\} \\
Q_{k} & =\left\{x \in \mathbb{H}:\left\langle x-x^{k}, x^{g}-x^{k}\right\rangle \leq 0\right\}, \\
A_{k} & =C_{k} \cap Q_{k} \cap C .
\end{aligned}
$$

Take $x^{k+1}=P_{A_{k}}\left(x^{g}\right)$, and go to Step 1 with $k$ is replaced by $k+1$.
Remark 1 (i) If $y^{k}=x^{k}$ then $x^{k}$ is a solution to $\mathrm{EP}(C, f)$;
(ii) If $y^{k}=x^{k}=t^{k}$ and $\alpha_{k}<1$ or $y^{k}=x^{k}=u^{k}$, then $x^{k} \in \operatorname{Sol}(C, f) \cap \operatorname{Fix}(T)$.

Firstly, let us recall the following lemma which was proved in [26]
Lemma 8 [26] Suppose that $p \in \operatorname{Sol}(C, f)$, then under assumptions $\left(A_{2}\right),\left(A_{3}\right)$, and ( $A_{4}$ ), we have:
(a) The linesearch is well defined;
(b) $f\left(z^{k}, x^{k}\right)>0$;
(c) $0 \notin \partial_{2} f\left(z^{k}, x^{k}\right)$;
(d)

$$
\begin{equation*}
\left\|v^{k}-p\right\|^{2} \leq\left\|x^{k}-p\right\|^{2}-\gamma_{k}\left(2-\gamma_{k}\right)\left(\sigma_{k}\left\|w^{k}\right\|\right)^{2} . \tag{20}
\end{equation*}
$$

Theorem 2 Suppose that the set $S=\operatorname{Sol}(C, f) \cap \operatorname{Fix}(T)$ is nonempty, the bifunction $f$ satisfies assumptions $\left(A_{1}\right)$ on $\Omega,\left(A_{2}\right)$, and $\left(A_{3}\right)$ on $C$, the mapping $T$ satisfies assumption $\left(A_{5}\right)$. Then the sequences $\left\{x^{k}\right\},\left\{u^{k}\right\}$ generated by Algorithm 2 converge strongly to the solution $x^{*}=P_{S}\left(x^{g}\right)$.

Proof Take $q \in S$. Since $\gamma_{k} \in[\underline{\gamma}, \bar{\gamma}] \subset(0,2)$, we get from Lemma 8 that

$$
\begin{equation*}
\left\|v^{k}-q\right\| \leq\left\|x^{k}-q\right\| \tag{21}
\end{equation*}
$$

By definition of $t^{k}$, we have

$$
\begin{aligned}
\left\|t^{k}-q\right\|^{2} & =\left\|\alpha_{k}\left(x^{k}-q\right)+\left(1-\alpha_{k}\right)\left(T x^{k}-q\right)\right\|^{2} \\
& =\alpha_{k}\left\|x^{k}-q\right\|^{2}+\left(1-\alpha_{k}\right)\left\|T x^{k}-q\right\|^{2}-\alpha_{k}\left(1-\alpha_{k}\right)\left\|T x^{k}-x^{k}\right\|^{2}
\end{aligned}
$$

Since $T$ is a $(\alpha, \beta, \gamma, \delta)$-symmetric generalized hybrid mapping with $\alpha+2 \beta+\gamma \geq 0$, $\alpha+\beta>0, \delta \geq 0$. By Lemma 5 it is quasi-nonexpansive, so

$$
\begin{equation*}
\left\|t^{k}-q\right\| \leq\left\|x^{k}-q\right\| \tag{22}
\end{equation*}
$$

Similarly,

$$
\begin{equation*}
\left\|u^{k}-q\right\| \leq\left\|x^{k}-q\right\| . \tag{23}
\end{equation*}
$$

Next, we show that $S \subset C_{k} \cap Q_{k}, \forall k$. Indeed, from (23) it implies that $q \in C_{k}$, or $S \subset C_{k}$. We prove $S \subset Q_{k}$ by induction, it is clear that $S \subset Q_{0}$. If $S \subset Q_{k}$, i.e., $\langle q-$ $\left.x^{k}, x^{g}-x^{k}\right\rangle \leq 0, \forall q \in S$. Since $x^{k+1}=P_{A_{k}}\left(x^{g}\right)$ we obtain $\left\langle x-x^{k+1}, x^{g}-x^{k+1}\right\rangle \leq$ $0, \forall x \in A_{k}$. Especially, $\left\langle q-x^{k+1}, x^{g}-x^{k+1}\right\rangle \leq 0, \forall q \in S$. So $S \subset C_{k} \cap Q_{k}, \forall k$. From definition of $Q_{k}$, it implies that $x^{k}=P_{Q_{k}}\left(x^{g}\right)$, so $\left\|x^{k}-x^{g}\right\| \leq\left\|x-x^{g}\right\|, \forall x \in$ $Q_{k}$. In particular

$$
\begin{equation*}
\left\|x^{k}-x^{g}\right\| \leq\left\|q-x^{g}\right\|, \quad \forall k, \quad \forall q \in S \tag{24}
\end{equation*}
$$

Consequently, $\left\{x^{k}\right\}$ is bounded. Combining with (22) and (23), we get $\left\{t^{k}\right\},\left\{u^{k}\right\}$ are also bounded.
In addition,

$$
\begin{aligned}
\left\|x^{k+1}-x^{k}\right\|^{2} & =\left\|x^{k+1}-x^{g}+x^{g}-x^{k}\right\|^{2} \\
& =\left\|x^{k+1}-x^{g}\right\|^{2}+\left\|x^{g}-x^{k}\right\|^{2}+2\left\langle x^{k+1}-x^{g}, x^{g}-x^{k}\right\rangle \\
& =\left\|x^{k+1}-x^{g}\right\|^{2}-\left\|x^{g}-x^{k}\right\|^{2}+2\left\langle x^{k+1}-x^{k}, x^{g}-x^{k}\right\rangle .
\end{aligned}
$$

Since $x^{k+1} \in Q_{k}$, it implies from the above inequality that

$$
\begin{equation*}
\left\|x^{k+1}-x^{k}\right\|^{2} \leq\left\|x^{k+1}-x^{g}\right\|^{2}-\left\|x^{k}-x^{g}\right\|^{2} \tag{25}
\end{equation*}
$$

Therefore $\left\{\left\|x^{k}-x^{g}\right\|\right\}$ is nondecreasing sequence. Together with (24), the limit $\lim _{k \rightarrow \infty}\left\|x^{k}-x^{g}\right\|$ does exist.
Hence, it also follows from (25) that

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|x^{k+1}-x^{k}\right\|=0 \tag{26}
\end{equation*}
$$

Because $x^{k+1} \in C_{k}$, it implies that

$$
\begin{aligned}
\left\|u^{k}-x^{k}\right\| & \leq\left\|u^{k}-x^{k+1}\right\|+\left\|x^{k+1}-x^{k}\right\| \\
& \leq 2\left\|x^{k+1}-x^{k}\right\|
\end{aligned}
$$

therefore, we deduce from (26) that

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|u^{k}-x^{k}\right\|=0 \tag{27}
\end{equation*}
$$

Besides that $\lim _{k \rightarrow \infty} \alpha_{k}=1$, so

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|t^{k}-x^{k}\right\|=\lim _{k \rightarrow \infty}\left(1-\alpha_{k}\right)\left\|x^{k}-T x^{k}\right\|=0 \tag{28}
\end{equation*}
$$

It is clear that

$$
\begin{aligned}
\left\|u^{k}-q\right\|^{2} & =\left\|\beta_{k}\left(t^{k}-q\right)+\left(1-\beta_{k}\right)\left(T v^{k}-q\right)\right\|^{2} \\
& =\beta_{k}\left\|t^{k}-q\right\|^{2}+\left(1-\beta_{k}\right)\left\|T v^{k}-q\right\|^{2}-\beta_{k}\left(1-\beta_{k}\right)\left\|t^{k}-T v^{k}\right\|^{2} \\
& \leq \beta_{k}\left\|t^{k}-q\right\|^{2}+\left(1-\beta_{k}\right)\left\|T v^{k}-q\right\|^{2} .
\end{aligned}
$$

In view of (22) and Lemma 8, yields

$$
\left\|u^{k}-q\right\|^{2} \leq\left\|x^{k}-q\right\|^{2}-\left(1-\beta_{k}\right) \gamma_{k}\left(2-\gamma_{k}\right)\left(\sigma_{k}\left\|w^{k}\right\|\right)^{2} .
$$

Hence

$$
\begin{equation*}
\left(1-\beta_{k}\right) \gamma_{k}\left(2-\gamma_{k}\right)\left(\sigma_{k}\left\|w^{k}\right\|\right)^{2} \leq\left\|x^{k}-u^{k}\right\|\left[\left\|x^{k}-q\right\|+\left\|u^{k}-q\right\|\right] . \tag{29}
\end{equation*}
$$

Since $0<1-\bar{\beta} \leq 1-\beta_{k} ; \gamma_{k} \in[\underline{\gamma}, \bar{\gamma}] \subset(0,2)$, and (27), we get from (29) that

$$
\begin{equation*}
\lim _{k \rightarrow \infty} \sigma_{k}\left\|w^{k}\right\|=0 \tag{30}
\end{equation*}
$$

Because $v^{k}=P_{C}\left(x^{k}-\gamma_{k} \sigma_{k} w^{k}\right)$, one has

$$
\left\|v^{k}-x^{k}\right\| \leq \gamma_{k} \sigma_{k}\left\|w^{k}\right\| .
$$

Combining with (30) we get

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|v^{k}-x^{k}\right\|=0 \tag{31}
\end{equation*}
$$

By definition of $u^{k}$, we have $\left(1-\beta_{k}\right) T v^{k}=u^{k}-\beta_{k} t^{k}$. Hence

$$
\begin{aligned}
(1-\bar{\beta})\left\|T v^{k}-v^{k}\right\| & \leq\left\|\left(1-\beta_{k}\right) T v^{k}-\left(1-\beta_{k}\right) v^{k}\right\| \\
& =\left\|u^{k}-v^{k}-\beta_{k}\left(t^{k}-v^{k}\right)\right\| \\
& \leq\left\|u^{k}-v^{k}\right\|+\beta_{k}\left\|t^{k}-v^{k}\right\| \\
& \leq\left\|u^{k}-x^{k}\right\|+\beta_{k}\left\|t^{k}-x^{k}\right\|+\left(1+\beta_{k}\right)\left\|x^{k}-v^{k}\right\| .
\end{aligned}
$$

Combining this fact with (27), (28), and (31), we receive in the limit that

$$
\begin{equation*}
\lim _{k \rightarrow \infty}\left\|T v^{k}-v^{k}\right\|=0 \tag{32}
\end{equation*}
$$

By Lemma 4, $\left\{y^{k}\right\}$ is bounded, consequently $\left\{z^{k}\right\}$ is bounded. From Lemma 3, $\left\{w^{k}\right\}$ is bounded. In view of ( 30 ) yields

$$
\begin{equation*}
\lim _{k \rightarrow \infty} f\left(z^{k}, x^{k}\right)=\lim _{k \rightarrow \infty}\left[\sigma_{k}\left\|w^{k}\right\|\right]\left\|w^{k}\right\|=0 \tag{33}
\end{equation*}
$$

We have

$$
\begin{aligned}
0=f\left(z^{k}, z^{k}\right) & =f\left(z^{k},\left(1-\eta_{k}\right) x^{k}+\eta_{k} y^{k}\right) \\
& \leq\left(1-\eta_{k}\right) f\left(z^{k}, x^{k}\right)+\eta_{k} f\left(z^{k}, y^{k}\right)
\end{aligned}
$$

so, we get from (19) that

$$
\begin{aligned}
f\left(z^{k}, x^{k}\right) & \geq \eta_{k}\left[f\left(z^{k}, x^{k}\right)-f\left(z^{k}, y^{k}\right)\right] \\
& \geq \frac{\mu}{2 \rho_{k}} \eta_{k}\left\|x^{k}-y^{k}\right\|^{2} .
\end{aligned}
$$

Combining with (33) one has

$$
\begin{equation*}
\lim _{k \rightarrow \infty} \eta_{k}\left\|x^{k}-y^{k}\right\|^{2}=0 \tag{34}
\end{equation*}
$$

Next, we show that any weak accumulation point of $\left\{x^{k}\right\}$ belongs to $S$. Indeed, suppose that $\left\{x^{k_{i}}\right\} \subset\left\{x^{k}\right\}$ and $x^{k_{i}} \rightharpoonup p$ as $i \rightarrow \infty$.
From (34) we get

$$
\begin{equation*}
\lim _{i \rightarrow \infty} \eta_{k_{i}}\left\|x^{k_{i}}-y^{k_{i}}\right\|^{2}=0 \tag{35}
\end{equation*}
$$

We now consider two distinct cases:
Case 1. $\lim \sup _{i \rightarrow \infty} \eta_{k_{i}}>0$.
Without loss of generality, we may assume that there exists $\bar{\eta}>0$ such that $\eta_{k_{i}}>$ $\bar{\eta}, \forall i \geq i_{0}$, use this fact and from (35), one has

$$
\begin{equation*}
\lim _{i \rightarrow \infty}\left\|x^{k_{i}}-y^{k_{i}}\right\|=0 \tag{36}
\end{equation*}
$$

Remember that $x^{k} \rightharpoonup p$, together with (36), it implies that $y^{k_{i}} \rightharpoonup p$ as $i \rightarrow \infty$.

From assertation (i) of Lemma 7 we get

$$
\rho_{k_{i}}\left[f\left(x^{k_{i}}, y\right)-f\left(x^{k_{i}}, y^{k_{i}}\right)\right] \geq\left\langle x^{k_{i}}-y^{k_{i}}, y-y^{k_{i}}\right\rangle, \quad \forall y \in C .
$$

Hence

$$
\begin{equation*}
\rho_{k_{i}}\left[f\left(x^{k_{i}}, y\right)-f\left(x^{k_{i}}, y^{k_{i}}\right)\right] \geq-\left\|x^{k_{i}}-y^{k_{i}}\right\|\left\|y-y^{k_{i}}\right\| . \tag{37}
\end{equation*}
$$

Letting $i \rightarrow \infty$, by jointly weak continuity of $f$ and (36), we obtain in the limit from (37) that

$$
f(p, y)-f(p, p) \geq 0 .
$$

So

$$
f(p, y) \geq 0, \quad \forall y \in C
$$

which means that $p$ is a solution of $\operatorname{EP}(C, f)$.
Case 2. $\lim _{i \rightarrow \infty} \eta_{k_{i}}=0$.
From the boundedness of $\left\{y^{k_{i}}\right\}$, without loss of generality we may assume that $y^{k_{i}} \rightharpoonup \bar{y}$ as $i \rightarrow \infty$.
Replacing $y$ by $x^{k_{i}}$ in (i) of Lemma 7 we get

$$
\begin{equation*}
f\left(x^{k_{i}}, y^{k_{i}}\right) \leq-\frac{1}{\rho_{k_{i}}}\left\|y^{k_{i}}-x^{k_{i}}\right\|^{2} . \tag{38}
\end{equation*}
$$

In the other hand, by the Armijo linesearch rule (19), for $m_{k_{i}}-1$, we have

$$
\begin{equation*}
f\left(z^{k_{i}, m_{k_{i}}-1}, x^{k_{i}}\right)-f\left(z^{k_{i}, m_{k_{i}}-1}, y^{k_{i}}\right)<\frac{\mu}{2 \rho_{k_{i}}}\left\|y^{k_{i}}-x^{k_{i}}\right\|^{2} . \tag{39}
\end{equation*}
$$

Combining with (38) we get

$$
\begin{equation*}
f\left(x^{k_{i}}, y^{k_{i}}\right) \leq-\frac{1}{\rho_{k_{i}}}\left\|y^{k_{i}}-x^{k_{i}}\right\|^{2} \leq \frac{2}{\mu}\left[f\left(z^{k_{i}, m_{k_{i}}-1}, y^{k_{i}}\right)-f\left(z^{k_{i}, m_{k_{i}}-1}, x^{k_{i}}\right)\right] . \tag{40}
\end{equation*}
$$

According to the algorithm, we have $z^{k_{i}, m_{k_{i}}-1}=\left(1-\eta^{m_{k_{i}}-1}\right) x^{k_{i}}+\eta^{m_{k_{i}}-1} y^{k_{i}}$, $\eta^{k_{i}, m_{k_{i}}-1} \rightarrow 0$ and $x^{k_{i}}$ converges weakly to $p, y^{k_{i}}$ converges weakly to $\bar{y}$, it implies that $z^{k_{i}, m_{k_{i}}-1} \rightharpoonup p$ as $i \rightarrow \infty$. Beside that $\left\{\frac{1}{\rho \rho_{i}}\left\|y^{k_{i}}-x^{k_{i}}\right\|^{2}\right\}$ is bounded, without loss of generality, we may assume that $\lim _{i \rightarrow+\infty} \frac{1}{\rho_{k_{i}}}\left\|y^{k_{i}}-x^{k_{i}}\right\|^{2}$ exists. Hence, we get in the limit from (40) that

$$
f(p, \bar{y}) \leq-\lim _{i \rightarrow+\infty} \frac{1}{\rho_{k_{i}}}\left\|y^{k_{i}}-x^{k_{i}}\right\|^{2} \leq \frac{2}{\mu} f(p, \bar{y}) .
$$

Therefore, $f(p, \bar{y})=0$ and $\lim _{i \rightarrow+\infty}\left\|y^{k_{i}}-x^{k_{i}}\right\|^{2}=0$. By the Case 1, it is immediate that $p$ is a solution of $\operatorname{EP}(C, f)$.

In addition, from (31) and (32), we have $v^{k_{i}} \rightharpoonup p$ and $\lim _{i \rightarrow \infty}\left\|T v^{k_{i}}-v^{k_{i}}\right\|=0$. By Lemma 6, $I-T$ is demiclosed at zero, we get $T p=p$, i.e., $p \in \operatorname{Fix}(T)$.
Hence $p \in S$.
Now, we set $x^{*}=P_{S}\left(x^{g}\right)$. From (24) one has,

$$
\begin{equation*}
\left\|x^{k}-x^{g}\right\| \leq\left\|x^{*}-x^{g}\right\|, \quad \forall k \tag{41}
\end{equation*}
$$

We get from Lemma 2 that $x^{k}$ converges strongly to $x^{*}$. Combining with (27) we also have that $u^{k}$ converges strongly to $x^{*}$. The proof is completed.

An example and preliminary computational results. To illustrate the proposed algorithms, we consider a problem when the bifunction $f$ and the mapping $T$ are given as follows

$$
\begin{aligned}
f(x, y) & =(P x+Q y+r)^{T}(y-x), \\
T x & =(I+U)^{-1} x,
\end{aligned}
$$

where $P=\left(p_{i j}\right)_{n \times n}, Q=\left(q_{i j}\right)_{n \times n}, U=\left(u_{i j}\right)_{n \times n}$ are $n \times n$ symmetric positive semidefinite matrices such that $P-Q$ is also positive semidefinite and $r \in \mathbb{R}^{n}$. The bifunction $f$ has the form of the one arising from a Nash-Cournot oligopolistic electricity market equilibrium model [6] and that $f$ is convex in $y$, Lipschitz-type continuous with constants $L_{1}=L_{2}=\frac{1}{2}\|P-Q\|$, and the positive semidefinition of $P-Q$ implies that $f$ is monotone [26]. It is clear that the set of fixed points of mapping $T$ is the solution set of the equation $U x=0$. In order to ensure that the intersection of the solution set of $\operatorname{EP}(C, f)$ and the fixed points of the mapping $T$ is nonempty, we futher assume that the constraint set $C$ contains the original, $r=0$, and $U$ is a diagonal matrix such that $u_{i i}>0$, forall $i \in I_{0}$ and $u_{i i}=0$, forall $i \notin I_{0}$, for some index set $I_{0} \subset\{1,2, \ldots, n-1, n\}$.

We tested the proposed algorithms for this example in which $C$ is the box $C=$ $\prod_{i=1}^{n}[-10,10], P, Q, U$ are matrices of the form $A^{T} A$ with $A=\left(a_{i j}\right)_{n \times n}$ being randomly generated in the interval $[-5,5]$, starting point $x^{g}$ is randomly generated in $[-10,10]$ and the parameters: $\alpha_{0}=\beta_{0}=\frac{1}{2}, \alpha_{k}=1-\frac{1}{k+2}, \beta_{k}=\frac{1}{2}+\frac{1}{k+3}$, and $\rho_{k}=\frac{0.5}{\|P-Q\|}$ in Algorithm $1 ; \eta=0.98, \mu=0.4, \rho_{k}=0.5, \gamma_{k}=1$ in Algorithm 2.

We implement Algorithms 1 and 2 for this problem in Matlab R2013 running on a Desktop with Intel(R) Core(TM) 2Duo CPU E8400 3 GHz , and 3 GB RAM. To terminate the algorithms, we use the stopping criteria $\left\|x^{k+1}-x^{k}\right\|<\epsilon$ with a tolerance $\epsilon=0.01$.

The computation results on Algorithms 1 and 2 are reported in Tables 1 and 2 respectively, where
$N . P$ : the number of the tested problems;
average times: the average CPU-computation times (in s);
average iteration: the average number of iterations.
From the computed results reported in these tables, we can see that the computational time by Algorithm 1 is less than that by Algorithm 2, probably due to Lipschitz type condition of bifunction $f$ and the parameters $\rho_{k}$ is defined by $f$ in each problem.

Table 1 Results computed with Algorithm 1

| N.P | Size $(n)$ | Average times | Average iterations |
| :--- | :---: | :---: | :---: |
| 10 | 5 | 23.2484 | 826 |
| 10 | 10 | 34.7438 | 1445 |
| 10 | 20 | 87.1016 | 2346 |
| 10 | 30 | 157.5781 | 2715 |
| 10 | 50 | 255.4578 | 3839 |

Table 2 Results computed with Algorithm 2

| N.P | Size $(n)$ | Average times | Average iterations |
| :--- | :---: | :---: | :---: |
| 10 | 5 | 38.5938 | 904 |
| 10 | 10 | 106.3172 | 2242 |
| 10 | 20 | 163.1266 | 3050 |
| 10 | 30 | 250.9313 | 3001 |
| 10 | 50 | 359.1094 | 3592 |

## 5 Conclusion

We have introduced two iterative methods for finding a common point of the solution set of a pseudomonotone equilibrium problem and the set of fixed points of a symmetric generalized hybrid mapping in a real Hilbert space. The basic iteration used in this paper is the extragradient iteration with or without the incorporation of a linesearch procedure. The strong convergence of the iterates has been obtained.

Acknowledgments The authors would like to thank the referees for their helpful comments and remarks which helped them very much in revising the paper. This research was supported by Basic Science Research Program through the National Research Foundation of Korea (NRF) funded by the Ministry of Education (NRF-2013R1A1A2A10008908). The first author is supported by NAFOSTED, under the Project 101.01-2014-24.

## References

1. Anh, P.N.: A hybrid extragradient method extended to fixed point problems and equilibrium problems. Optimization 62, 271-283 (2013)
2. Anh, P.N., Muu, L.D.: A hybrid subgradient algorithm for nonexpansive mappings and equilibrium problems. Optim. Lett. 8, 727-738 (2014)
3. Bigi, G., Castellani, M., Pappalardo, M., Passacantando, M.: Existence and solution methods for equilibria. Eur. J. Oper. Res. 227, 1-11 (2013)
4. Blum, E., Oettli, W.: From optimization and variational inequalities to equilibrium problems. Math. Stud. 63, 127-149 (1994)
5. Ceng, L.C., Al-Homidan, S., Ansari, Q.H., Yao, J.C.: An iterative scheme for equilibrium problems and fixed point problems of strict pseudo-contraction mappings. J. Comput. Appl. Math. 223, 967-974 (2009)
6. Contreras, J., Klusch, M., Krawczyk, J.B.: Numerical solution to Nash-Cournot equilibria in coupled constraint electricity markets. EEE Trans. Power Syst. 19, 195-206 (2004)
7. Dinh, B.V., Muu, L.D.: A projection algorithm for solving pseudomonotone equilibrium problems and it's application to a class of bilevel equilibria. Optimization 64, 559-575 (2015)
8. Dinh, B.V., Hung, P.G., Muu, L.D.: Bilevel optimization as a regularization approach to pseudomonotone equilibrium problems. Numer. Funct. Anal. Optim. 35, 539-563 (2014)
9. Facchinei, F., Pang, J.S.: Finite-Dimensional Variational Inequalities and Complementarity Problems. Springer, New York (2003)
10. Genel, A., Lindenstrass, J.: An example concerning fixed points. Isr. J. Math. 22, 81-86 (1975)
11. Hojo, M., Suzuki, T., Takahashi, W.: Fixed point theorems and convergence theorems for generalized hybrid non-self mappings in Hilbert spaces. J. Nonlinear Convex Anal. 14, 363-376 (2013)
12. Ishikawa, S.: Fixed points by a new iteration method. Proc. Am. Math. Soc. 40, 147-150 (1974)
13. Itoh, S., Takahashi, W.: The common fixed point theory of single-valued mappings and multi-valued mappings. Pac. J. Math. 79, 493-508 (1978)
14. Kawasaki, T., Takahashi, W.: Existence and mean approximation of fixed points of generalized hybrid mappings in Hilbert spaces. J. Nonlinear Convex Anal. 14, 71-87 (2013)
15. Konnov, I.V.: Combined relaxation methods for variational inequalities. In: Lecture Notes in Economics and Mathematical Systems, vol. 495. Springer, Berlin (2001)
16. Korpelevich, G.M.: The extragradient method for finding saddle points and other problems. Matekon 12, 747-756 (1976)
17. Maingé, P.E.: A hybrid extragradient viscosity methods for monotone operators and fixed point problems. SIAM J. Control. Optim. 47, 1499-1515 (2008)
18. Moradlou, F., Alizadeh, S.: Strong convergence theorem by a new iterative method for equilibrium problems and symmetric generalized hybrid mappings. Mediterr. J. Math.13, 379-390 (2016)
19. Muu, L.D., Oettli, W.: Convergence of an adaptive penalty scheme for finding constrained equilibria. Nonlinear Anal. TMA 18, 1159-1166 (1992)
20. Nakajo, K., Takahashi, W.: Strong convergence theorems for nonexpansive mapping and nonexpansive semigroups. J. Math. Anal. Appl. 279, 372-379 (2003)
21. Plubtieng, S., Kumam, P.: Weak convergence theorem for monotone mappings and a countable family of nonexpansive semigroups. J. Comput. Appl. Math. 224, 614-621 (2009)
22. Rockafellar, R.T.: Convex Analysis. Princeton University Press, Princeton (1970)
23. Tada, A., Takahashi, W.: Weak and strong convergence theorem for nonexpansive mapping and equilibrium problem. J. Optim. Theory Appl. 133, 359-370 (2007)
24. Takahashi, W., Takeuchi, Y., Kubota, R.: Strong convergence theorems by hybrid methods for families of nonexpansive mappings in Hilbert spaces. J. Math. Anal. Appl. 341, 276-286 (2008)
25. Takahashi, W., Wong, N.C., Yao, J.C.: Fixed point theorems for new generalized hybrid mappings in Hilbert spaces and applications. Taiwan. J. Math. 17, 1597-1611 (2013)
26. Tran, D.Q., Dung, L.M., Nguyen, V.H.: Extragradient algorithms extended to equilibrium problems. Optimization 57, 749-776 (2008)
27. Vuong, P.T., Strodiot, J.J., Nguyen, V.H.: Extragradient methods and linesearch algorithms for solving Ky Fan inequalities and fixed point problems. J. Optim. Theory Appl. 155, 605-627 (2013)
28. Vuong, P.T., Strodiot, J.J., Nguyen, V.H.: On extragradient-viscosity methods for solving equilibrium and fixed point problems in a Hilbert space. Optimization 64, 429-451 (2015)
29. Yanes, C.M., Xu, H.K.: Strong convergence of the $C Q$ method for fixed point iteration processes. Nonlinear Anal. TMA 64, 2400-2411 (2006)

[^0]:    Do Sang Kim
    dskim@pknu.ac.kr
    Bui Van Dinh
    vandinhb@gmail.com
    1 Faculty of Information Technology, Le Quy Don Technical University, Hanoi, Vietnam
    2 Present Address: Department of Applied Mathematics, Pukyong National University, Busan 608-737, Korea

