# Interval Type-2 Fuzzy Co-Clustering Algorithm

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Abstract—This paper introduces a novel clustering technique by combining fuzzy co-clustering approach and interval type-2 fuzzy sets. The proposed algorithm is demonstrated through experiments on UC Berkeley image data-sets to conduct clustering on color images. The experimental results show that the clustering quality is better by evaluating using validity indexes in comparison with previous methods.

*Index Terms*—Interval Type-2 Fuzzy Clustering, Fuzzy Co-Clustering, Image Segmentation.

#### I. INTRODUCTION

Image data clustering is an unsupervised learning technique to divide the pixels into classes or clusters of similar color range. With color and multispectral images, data pixel has multiple features. The algorithm, that simultaneously clustering data points and features of data point, can be used to segment images. This algorithm is called co-clustering technique to extend the applicability and quality of clustering, combined with fuzzy logic is a need to better handle the uncertainty in the data.

Fuzzy clustering has been developed in both of theory and applications. Fuzzy C-Means Clustering (FCM) proposed by Bezdek [3] and its variants has been applied to various problems involving image segmentation [1]. Recently, type-2 fuzzy sets which are the extension of original fuzzy sets, have been developed and applied to many different problems [2], [12], [13], [14], [24], involving data clustering, due to advantage of handling uncertainty. C.Y. Yeh et al [27] introduced data-based system modeling using a type-2 fuzzy neural network with a hybrid learning algorithm. To extension the capabilities of data clustering, type-2 fuzzy sets have integrated with data clustering to achieves type-2 fuzzy clustering model. S. A. Begum et al [2] proposed a type-2 fuzzy clustering algorithm for magnetic resonance imaging segmentation. L. A. Lucas et al [11] introduced a method to classifying land cover based on general type-2 fuzzy classifiers. [12] M.U. Nguyen et al proposed an interval type-2 fuzzy subtractive clustering approach to obstacle detection of robot vision using RGB-D camera.

Fuzzy co-clustering [6], [9] is another approach for clustering complex data types as multi-dimensional, multi-feature, high size. Fuzzy co-clustering is used to classify the data type as Web data, color image data... W. Tjhi proposed various fuzzy clustering algorithms. Partitioning algorithm based on fuzzy co-clustering documents and words [18] that can initialize the fuzzy phrase structure obtained from natural distributions, meet needs restoration received information. [18] - [22] Long Thanh Ngo Department of Information Systems, Le Quy Don Technical University, 236 Hoang Quoc Viet, Hanoi, Vietnam E-mail: ngotlong@gmail.com

are the statistics fuzzy co-clustering algorithm, and heuristicbased fuzzy co-clustering (HFCC) and semi-supervised fuzzy co-clustering (SS-FCC) with dual partition approach, used to classify data types that have high dimensions. SS-FCC [22] proposed a semi-supervised techniques contract fuzzy clustering. In [10], authors proposed a method that comparison of imputation strategies in FNM-based and RFCM-based fuzzy co-clustering. The fuzzy co-clustering based on FNM and RFCM [15] outlined some fuzzy co-clustering algorithms. [5] was to improve the recommendation performance which is a combination of content-based and collaborative filtering approaches in a two-layer graph model getting use of web content and usage mining. [6] is considered as a new proposal in using fuzzy co-clustering model to segment color image data.

To combine the ability of handling uncertainty of type-2 fuzzy sets and processing multi-dimensional data, the paper propose an interval type-2 fuzzy co-clustering algorithm (IT2FCC). Experiments are implemented based on color image segmentation. The paper also extend the evaluation criteria to assess clustering quality. Experiments were conducted on set of sample image data includes 100 color photos, satellite images.

The paper is organized as follow: Section II provides the basic content of fuzzy set theory and type-1 fuzzy co-clustering algorithm. Section III introduces the proposed algorithm - IT2FCC. Section IV presents some experimental results. And section V concludes the paper and further works.

### II. BACKGROUND

This section give a briefly overview relate to interval type-2 clustering and fuzzy co-clustering.

## A. Type-2 Fuzzy Sets

Definition 2.1: A type - 2 fuzzy set, denoted  $\tilde{A}$ , is characterized by a type-2 membership function  $\mu_{\tilde{A}}(x, u)$  where  $x \in X$  and  $u \in J_x \subseteq [0, 1]$ , i. e.,

$$\tilde{A} = \{((x, u), \mu_{\tilde{A}}(x, u)) | \forall x \in X, \forall u \in J_x \subseteq [0, 1]\}$$
(1)

or

$$\tilde{A} = \int_{x \in X} \int_{u \in J_x} \mu_{\tilde{A}}(x, u)) / (x, u), J_x \subseteq [0, 1]$$
 (2)

in which  $0 \le \mu_{\tilde{A}}(x, u) \le 1$ , see [16].

At each value of x, say x = x', the 2-D plane whose axes are u and  $\mu_{\tilde{A}}(x', u)$  is called a *vertical slice* of  $\mu_{\tilde{A}}(x, u)$ . A secondary membership function is a vertical slice of  $\mu_{\tilde{A}}(x, u)$ . It is  $\mu_{\tilde{A}}(x = x', u)$  for  $x \in X$  and  $\forall u \in J_{x'} \subseteq [0, 1]$ , i. e.

$$\mu_{\tilde{A}}(x=x',u) \equiv \mu_{\tilde{A}}(x') = \int_{u \in J_{x'}} f_{x'}(u)/u, J_{x'} \subseteq [0,1] \quad (3)$$

in which  $0 \leq f_{x'}(u) \leq 1$ .

Type-2 fuzzy sets are called an interval type-2 fuzzy sets [17] if the secondary membership function  $f_{x'}(u) = 1 \quad \forall u \in J_x$  i. e. a type-2 fuzzy set are defined as follows:

Definition 2.2: An interval type-2 fuzzy set  $\tilde{A}$  is characterized by an interval type-2 membership function  $\mu_{\tilde{A}}(x, u) = 1$ where  $x \in X$  and  $u \in J_x \subseteq [0, 1]$ , i. e.,

$$\tilde{A} = \{((x, u), 1) | \forall x \in X, \forall u \in J_x \subseteq [0, 1]\}$$
(4)

Uncertainty of A, denoted FOU, is union of primary functions i. e.  $FOU(\tilde{A}) = \bigcup_{x \in X} J_x$ . Upper/lower bounds of membership function (UMF/LMF), denoted  $\overline{\mu}_{\tilde{A}}(x)$  and  $\underline{\mu}_{\tilde{A}}(x)$ , of  $\tilde{A}$ are two type-1 membership function and bounds of FOU which is limited by two membership functions of an type-1 fuzzy set are UMF and LMF.

# B. Fuzzy Co-Clustering

Fuzzy co-clustering (FCC) is a clustering method that performed in simultaneous fuzzy clustering of objects and features. The results of co-clusters which reflect the interrelations between object clusters and feature clusters. FCC have been studied, improvements and applications in [5], [6], [9], [18], [19], [20], [21], [22]. FCC provides two membership functions, the one is for the partition or data points and the one is for the components of the data points. The objective function  $J_{FCC}(U, V, P)$  is described as follows:

$$J_{FCC}(U, V, P) = \sum_{c=1}^{C} \sum_{i=1}^{N} \sum_{j=1}^{K} u_{ci} v_{cj} D_{cij} + T_U \sum_{c=1}^{C} \sum_{i=1}^{N} u_{ci} \log u_{ci} + T_V \sum_{c=1}^{C} \sum_{j=1}^{K} v_{cj} \log v_{cj} + \sum_{i=1}^{N} \lambda_i (\sum_{c=1}^{C} u_{ci} - 1) + \sum_{c=1}^{C} \gamma_c (\sum_{j=1}^{K} v_{cj} - 1)$$
(5)

The components of the objective function (5) is determined by the following formulas:  $u_{ci}$  is membership grade of data points, calculated as follows:

$$u_{ci} = \frac{e^{\left(-\sum_{j=1}^{K} \frac{v_{cj} D_{cij}}{T_U}\right)}}{\sum_{f=1}^{C} e^{\left(-\sum_{j=1}^{K} \frac{v_{fj} D_{cij}}{T_U}\right)}}$$
(6)

 $v_{cj}$  is membership grade of features/components of each data point, calculated as follows:

$$v_{cj} = \frac{e^{\left(-\sum_{i=1}^{N} \frac{u_{ci}D_{cij}}{T_V}\right)}}{\sum_{q=1}^{K} e^{\left(-\sum_{i=1}^{N} \frac{u_{ci}D_{ciq}}{T_V}\right)}}$$
(7)

# III. INTERVAL TYPE-2 FUZZY CO-CLUSTERING IN COLOR IMAGE SEGMENTATION

The idea of the Interval Type-2 Fuzzy Co-Clustering algorithm (IT2FCC) derived from the need to determine I image which obtained from a camera coincide with P image in the sample photo gallery. One of the methods that have been studied and conducted clustering both images I and P, then from clustering results to determine I and P coincide or not. As above mention, there have been numerous studies involving the fuzzy clustering model, fuzzy co-clustering and type-2 fuzzy clustering. In this section, we present the proposed algorithm, called Interval Type-2 Fuzzy Co-Clustering.

The first, we represent color image I with size  $W \times H = N$ as a set X of N pixels and

$$X = \{x_1, x_2, ..., x_i, ..., x_N\} \in \mathbb{R}^K$$

K is the number of features of each pixel (K = 3 in RGB color space). Let  $x_{ij}$  denote the  $j^{th}$  feature of the  $i^{th}$  data pixel,  $p_{cj}$  be the prototype of clusters and  $D_{cij}$ =Dist $(x_{ij}, p_{cj})$  be the square of Euclidean distance between feature data pixel  $x_{ij}$  and the feature centroid  $p_{cj}$ , given by:

$$D_{cij} = d^2(x_{ij}, p_{cjj}) = (x_{ij} - p_{cj})^2$$
(8)

Let  $c_{ci}$  denote the object membership grade of the  $i^{th}$  data pixel to  $c^{th}$  cluster,  $U = \{u_{ci}\}$  be the  $C \times N$  object membership grade matrix of image I,  $v_{cj}$  denotes the feature membership grade defined as the membership of feature  $j^{th}$ to the  $c^{th}$  cluster and  $V = \{v_{cj}\}$  be the corresponding  $C \times K$ feature membership matrix for image I.

The objective function of Type-2 Fuzzy Co-Clustering algorithm  $J_{T2FCC}(U, V, P)$  is described as follows:

$$J_{T2FCC}(U, V, P) = \sum_{c=1}^{C} \sum_{i=1}^{N} \sum_{j=1}^{K} u_{ci}^{m} v_{cj}^{m} D_{cij} + I_{U} \sum_{c=1}^{C} \sum_{i=1}^{N} u_{ci}^{m} \log u_{ci}^{m} + T_{V} \sum_{c=1}^{C} \sum_{j=1}^{K} v_{cj}^{m} \log v_{cj}^{m} + \sum_{i=1}^{N} \lambda_{i} (\sum_{c=1}^{C} u_{ci}^{m} - 1) + \sum_{c=1}^{C} \gamma_{c} (\sum_{j=1}^{K} v_{cj}^{m} - 1)$$
(9)

To get optimal clustering results, the (9) reaches a minimum and  $J_{T2FCC}$  is minimized subject to the following constraints:

$$\sum_{c=1}^{C} u_{ci} = 1, u_{ci} \in [0, 1], \forall i = \overline{1, N}$$
$$\sum_{j=1}^{K} v_{cj} = 1, v_{cj} \in [0, 1], \forall c = \overline{1, C}$$
(10)

Where  $\lambda_i, \gamma_c$  are Lagrange coefficients,  $T_u$  and  $T_v$  are weights that indicate fuzziness. Increasing  $T_U$  and  $T_V$  will increase the opacity of the cluster.  $x_{ij}$  is  $j^{th}$  element of  $i^{th}$  data point,  $P = \{p_{cj}\}$  be the set of feature centroids.

To determine the value of the objective function (9), we need to find formulas of the membership matrices  $u_{ci}$ ,  $v_{cj}$  and distance  $D_{cij}$ .

Firstly, taking the partial derivative of J(U, V, P) in (9) with respect to U and setting the gradient to zero, we have,

$$\frac{\partial J}{\partial U} = \sum_{j=1}^{K} v_{cj}^m D_{cij} + T_U(m \log u_{ci} + 1) + \lambda_i = 0 \qquad (11)$$

Subjecting  $u_{ci}$  derived from (11) to the constraint in (10), we obtain the formula  $u_{ci}$  as follows:

$$u_{ci} = \frac{e^{\left(-\sum_{j=1}^{K} \frac{v_{cj}^m D_{cij}}{mT_U}\right)}}{\sum_{c=1}^{C} e^{\left(-\sum_{j=1}^{K} \frac{v_{cj}^m D_{cij}}{mT_U}\right)}}$$
(12)

In a similar manner, taking the partial derivative of J(U, V, P) with respect to V and setting the gradient to zero we have,

$$\frac{\partial J}{\partial V} = \sum_{i=1}^{N} u_{ci}^m D_{cij} + T_V(m \log v_{cj} + 1) + \gamma_c = 0 \qquad (13)$$

Applying the constraint (10) to  $v_{cj}$  derived from (13) , we obtain the formula for the feature membership function  $v_{cj}$  as follows:

$$v_{cj} = \frac{e^{\left(-\sum_{i=1}^{N} \frac{u_{ci}^m D_{cij}}{mT_V}\right)}}{\sum_{j=1}^{K} e^{\left(-\sum_{i=1}^{N} \frac{u_{ci}^m D_{cij}}{mT_V}\right)}}$$
(14)

Take the partial derivative of J(U, V, P) with respect to P and setting the gradient to zero, we have,

$$\frac{\partial J}{\partial P} = v_{cj}^m \sum_{i=1}^N u_{ci}^m x_{ij} - v_{cj}^m p_{cj} \sum_{i=1}^N u_{ci}^m = 0$$
(15)

and finally, from (15), we have,

$$p_{cj} = \frac{\sum_{i=1}^{N} u_{ci}^{m} x_{ij}}{\sum_{i=1}^{N} u_{ci}^{m}}$$
(16)

IT2FCC is extension of fuzzy co-clustering by using two fuzziness parameters  $m_1$ ,  $m_2$  to make a FOU, corresponding to upper and lower values of fuzzy co-clustering. The use of fuzzifiers gives two objective functions to be minimized as follows:

$$J_{m_1}(U, V, P) = \sum_{c=1}^{C} \sum_{i=1}^{N} \sum_{j=1}^{K} u_{ci}^{m_1} v_{cj}^{m_1} D_{cij} + T_U \sum_{c=1}^{C} \sum_{i=1}^{N} u_{ci}^{m_1} \log u_{ci}^{m_1} + T_V \sum_{c=1}^{C} \sum_{j=1}^{K} v_{cj}^{m_1} \log v_{cj}^{m_1} + \sum_{i=1}^{N} \lambda_i (\sum_{c=1}^{C} u_{ci}^{m_1} - 1) + \sum_{c=1}^{C} \gamma_c (\sum_{j=1}^{K} v_{cj}^{m_1} - 1)$$
(17)

and

$$J_{m_2}(U, V, P) = \sum_{c=1}^{C} \sum_{i=1}^{N} \sum_{j=1}^{K} u_{ci}^{m_2} v_{cj}^{m_2} D_{cij} + T_U \sum_{c=1}^{C} \sum_{i=1}^{N} u_{ci}^{m_2} \log u_{ci}^{m_2} + T_V \sum_{c=1}^{C} \sum_{j=1}^{K} v_{cj}^{m_2} \log v_{cj}^{m_2} + \sum_{i=1}^{N} \lambda_i (\sum_{c=1}^{C} u_{ci}^{m_2} - 1) + \sum_{c=1}^{C} \gamma_c (\sum_{j=1}^{K} v_{cj}^{m_2} - 1)$$
(18)

Upper/lower degrees of membership  $\bar{u} ci$  and  $\underline{u}_{ci}$  are determined as follows:

$$\overline{u}_{ci} = \frac{e^{\left(-\sum_{j=1}^{K} \frac{v_{cj}^{m1} D_{cij}}{m_1 T_U}\right)}}{\sum_{f=1}^{C} e^{\left(-\sum_{j=1}^{K} \frac{v_{fj}^{m1} D_{fij}}{m_1 T_U}\right)}}$$

and

$$\underline{u}_{ci} = \frac{e^{\left(-\sum\limits_{j=1}^{K} \frac{v_{cj}^{m_2} D_{cij}}{m_2 T_U}\right)}}{\sum\limits_{f=1}^{C} e^{\left(-\sum\limits_{j=1}^{K} \frac{v_{cj}^{m_2} D_{fij}}{m_2 T_U}\right)}}$$

Meanwhile, we conducted defuzzification and obtained  $u_{ci}$  as following:

$$u_{ci} = \frac{\overline{u}_{ci} + \underline{u}_{ci}}{2} \tag{19}$$

In the same way, upper/lower degrees of membership, and are determined as follows:

$$\overline{v}_{cj} = \frac{e^{\left(-\sum_{i=1}^{N} \frac{u_{ci}^{m1} D_{cij}}{m_1 T_V}\right)}}{\sum_{j=1}^{K} e^{\left(-\sum_{i=1}^{N} \frac{u_{ci}^{m1} D_{cij}}{m_1 T_V}\right)}}$$

and

$$\underline{v}_{cj} = \frac{e^{\left(-\sum\limits_{i=1}^{N}\frac{u_{ci}^{m^{2}}D_{cij}}{m_{2}T_{V}}\right)}}{\sum\limits_{j=1}^{K}e^{\left(-\sum\limits_{i=1}^{N}\frac{u_{ci}^{m^{2}}D_{cij}}{m_{2}T_{V}}\right)}}$$

 $v_{cj}$  is defined as follows:

$$v_{cj} = \frac{\overline{v}_{cj} + \underline{v}_{cj}}{2} \tag{20}$$

With  $\overline{p}_{cj}$  and  $\underline{p}_{cj}$ , we have,

$$\overline{p}_{cj} = \frac{\sum_{i=1}^{N} u_{ci}^{m1} x_{ij}}{\sum_{i=1}^{N} u_{ci}^{m1}}$$

and

$$\underline{p}_{cj} = \frac{\sum_{i=1}^{N} u_{ci}^{m^2} x_{ij}}{\sum_{i=1}^{N} u_{ci}^{m^2}}$$

...

and

$$p_{cj} = \frac{\overline{p}_{cj} + \underline{p}_{cj}}{2} \tag{21}$$

IT2FCC algorithm perform the following steps:

1. Initialize the parameters  $T_u$ ,  $T_v$ ,  $m_1$ ,  $m_2$ , maximum error limit and maximum number of iterations max.

- 2. Set iteration number  $\tau = 1$ .
- 3. Initialize  $u_{ci}$  such that  $0 \le u_{ci} \le 1$ .
- 4. DO
- 5. Calculate  $p_{cj}$  using (21)
- 6. Calculate  $D_{cij}$  using (8).
- 7. Calculate  $v_{cj}$  using (20).
- 8. Calculate  $u_{ci}$  using (19).
- 9. Increase  $\tau = \tau + 1$ .
- 10. WHILE  $(max(|u_{ci}[\tau+1] u_{ci}[\tau]|) \le \varepsilon$  or  $\tau = \tau_{max}$ ) 11. Output result.

# IV. EXPERIMENTAL RESULTS

# A. Validity indexes

, and

Fuzzy clustering in general, type-2 fuzzy co-clustering in particular are unsupervised learning process, the data objects are not labeled and anticipated structure.

Xie and Beni [7] proposed the validity function S of the clusters as follows:

$$S(c) = \frac{\sigma/N}{d_{\min}} \tag{22}$$

Where  $d_{min}$  is evaluated from

$$d_{\min} = \min_{\forall c} \left\{ \sum_{j=1}^{K} \left( p_{(c+1)j} - p_{cj} \right)^2 \right\}$$
(23)

where  $d_{min}$  is the minimum distance between the centroids  $p_{cj}$  for cluster c = 1, ..., C and feature j and  $\sigma$  is the maximum variance among all the clusters C, given by

$$\sigma = \max_{\forall c} \left\{ \sum_{i=1}^{N} u_{ci}^2 \sum_{j=1}^{K} (x_{ij} - p_{cj})^2 \right\}$$
(24)

H.L Shieh [23] defined cluster validity measure the separation between clusters and the compactness in each cluster to indicate the optimal cluster number obtained by fuzzy clustering algorithms as follows,

$$CS(c) = Com(c)xSE(c)$$
<sup>(25)</sup>

where, Com(c) is measure compactness in each cluster, defined as follows,

$$Com(c) = \left(\frac{1}{N} \sum_{c=1}^{C} \sum_{i=1}^{N} u_{ci} \|x_i - p_c\| \mathbf{w}_{ci}\right)^2$$

 $w_{ci} = \exp(-\frac{\|x_i - p_c\|^2}{2\sigma})$  (26)

and SE(c) is measure the separation between clusters, defined as follows

$$SE(c) = \frac{1}{\frac{\sqrt{\sum_{i=1}^{C} \sum_{k=1}^{C} \|p_i - p_c\|}}{\frac{c(c-1)}{2}} \sqrt{\min_{i \neq j}(\|p_i - p_j\|)}}$$
(27)

The better algorithms exhibit smaller values of S and CS. Therefore, we can determine the optimal number of clusters by searching the minimal value of  $S(c^*)$  or  $CS(c^*)$  and  $c^*$  is the optimal number of clusters.

To assess the quality of clustering, we need to use a set of appropriate indicators of the parameters related to the clustering algorithm respectively. There have been many studies around the development of clustering assessment criteria, but studies are limited to the fuzzy clustering algorithm, and fuzzy co-clustering. Bezdek [4] proposed two coefficients, that are Partition Coefficient (PC) and Partition Entropy (PE):

$$PC = \frac{1}{N} \sum_{c=1}^{C} \sum_{i=1}^{N} u_{ci}^2$$
(28)

and

$$PE = -\frac{1}{C} \sum_{c=1}^{C} \sum_{i=1}^{N} u_{ci} \log u_{ci}$$

The better algorithms exhibit smaller values of PE and the larger value of PC. So, the optimal partition can be the one having larger PC (or smaller PE). In fuzzy co-clusstering, the validity indexes are not only object membership grades  $u_{ci}$  but also feature membership grades  $v_{cj}$ . Meanwhile, Honda [5] also adjusted the indexes PC and PE becoming four components PCu, PCw, PEu and PEw:

$$PC_u = \frac{1}{N} \sum_{c=1}^{C} \sum_{i=1}^{N} u_{ci}^2, PC_v = \frac{1}{C} \sum_{c=1}^{C} \sum_{j=1}^{K} v_{cj}^2$$
(29)

$$PE_u = -\frac{1}{N} \sum_{c=1}^{C} \sum_{i=1}^{N} u_{ci} \log u_{ci}, PE_v = -\frac{1}{C} \sum_{c=1}^{C} \sum_{i=1}^{K} v_{cj} \log v_{cj}$$

To assess the quality of image segmentation, we use two indexes, Mean Squared Error (MSE)[25] and Image Quality Index (IQI)[26]:

$$MSE(x,y) = \frac{1}{N} \sum_{i=1}^{N} (x_i - y_i)$$
(30)

$$IQI = \frac{4\sigma_{xy}\overline{xy}}{(\sigma_x^2 + \sigma_y^2)(\overline{x}^2 + \overline{y}^2)}$$
(31)

with  $\overline{x} = \frac{1}{N} \sum_{i=1}^{N} x_i, \overline{y} = \frac{1}{N} \sum_{i=1}^{N} y_i, \ \sigma_x^2 = \frac{1}{N-1} \sum_{i=1}^{N} (x_i - \overline{x}),$   $\sigma_y^2 = \frac{1}{N-1} \sum_{i=1}^{N} (y_i - \overline{y}) \text{ and } \sigma_{xy} = \frac{1}{N-1} \sum_{i=1}^{N} (x_i - \overline{x})(y_i - \overline{y})$ Where,  $x = \{x_i\} = \{x_1, x_2, ..., x_N\}$  and  $y = \{y_i\} = \{y_1, y_2, ..., y_N\}$  corresponding to the original image and segmented image.

Thus, the better algorithms exhibit the smaller value of PE, MSE and the larger value of PC, IQI.

No.	Original image	Results of FCM		Results o	fFCC	Results of IT2FCC	
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-			IQI: 0.8549		IQI: 0.8587		IQI: 0.9324
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					CS: 0.787		
	1 A A A		PCu: 0.4592	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	PC <sub>u</sub> : 0.9650		PCu: 0.9872
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			PCu: 0.3680		PCu: 0.9680		PCu: 0.9827
			PE <sub>2</sub> : 0.37121		PE <sub>u</sub> : 0.00148		PE <sub>u</sub> : 0.01335
6			IOL 0 0016		MaE: 20./1		MaE: 22.33
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		1 6 2 1	PE.: 0 30734	1.1.1.1	PE.: 0.00128	1. 200	PE.: 0.01250
			MSE: 24.65		MSE: 25.34		MSE: 23.25
7			IOI: 0.9128	$\sim 0$	IOI: 0.9304	$\sim - 0$	IOI: 0.9536
	4 4 4 4 4 4						
	1000			Charles and		1.	
		1	PC <sub>u</sub> : 0.5242		PCu: 0.8693	1	PC <sub>u</sub> : 0.9962
	AL AL	E Ela	PE <sub>4</sub> : 0.38783	E E	PE <sub>u</sub> : 0.00039	A B	PE <sub>u</sub> : 0.00298
•		The line	MSE: 45.63	TOTAL 1	MSE: 42.62		MSE: 34.36
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			PE <sub>4</sub> : 0.33718	and the second second	PE <sub>u</sub> : 0.00105	and the second s	PE <sub>u</sub> : 0.00771
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			PC <sub>4</sub> : 0.7841		PC <sub>4</sub> : 0.8369		PCu: 0.9964
		the second is	PE <sub>2</sub> : 0.196/8		PEg: 0.00031	-	MCE, 19.55
10			INIS E: 20.97		TOT: 0.0240		TOT: 0.0002
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Fig. 1. Image segmentation results on 10 sampple images using FCM, FCC and IT2FCC

TABLE I	
COLOR IMAGE SEGMENTATION RESULTS USING IT2FCC WITH DIFFERENT NUMBER	OF CLUSTERS

No	Туре	С	Κ	PCu	PEu	MSE	IQI	S	CS
1	FCM	3	15	0.7332	0.20602	39.44	0.9344	0.1631	0.010
	FCC	3	12	0.9399	0.00018	44.07	0.8754	0.0610	0.035
	IT2FCC	3	35	0.9972	0.00219	36.95	0.9569	0.0649	0.057
2	FCM	4	26	0.6949	0.25638	32.72	0.9524	0.1052	0.044
2	FCC	4	32	0.9704	0.00037	32.61	0.9505	0.0474	0.030
	IT2FCC	4	34	0.9952	0.00379	30.67	0.9736	0.0392	0.008
3	FCM	5	27	0.6225	0.32337	29.96	0.9643	0.3307	0.070
	FCC	5	35	0.9851	0.00089	28.68	0.9582	0.0736	0.108
	IT2FCC	5	43	0.9916	0.00647	27.14	0.9811	0.0598	0.102
4	FCM	6	28	0.5892	0.36517	27.12	0.9709	0.1989	0.076
-	FCC	6	60	0.9987	0.00096	22.70	0.9875	0.0524	0.074
	IT2FCC	6	39	0.9883	0.00898	22.71	0.9875	0.0498	0.186
5	FCM	7	26	0.5431	0.41882	26.61	0.9738	0.1338	0.172
	FCC	7	57	0.9978	0.00147	20.86	0.9898	0.0723	0.357
	IT2FCC	7	27	0.9841	0.01231	20.74	0.9899	0.0487	0.479
6	FCM	8	24	0.5162	0.45083	24.26	0.9770	0.8675	0.319
	FCC	8	35	0.9977	0.00165	19.63	0.9909	0.0556	0.302
	IT2FCC	8	44	0.9818	0.01381	19.64	0.9909	0.0529	0.237
7	FCM	9	26	0.4868	0.48969	23.39	0.9797	23.0918	0.191
'	FCC	9	34	0.9972	0.00199	18.66	0.9919	0.1039	0.275
	IT2FCC	9	36	0.9745	0.01976	18.67	0.9920	0.0925	0.258
8	FCM	10	27	0.4629	0.52590	22.76	0.9814	6.8071	0.196
	FCC	10	31	0.9970	0.00219	18.17	0.9925	0.0877	0.263
	IT2FCC	10	38	0.9711	0.02231	18.01	0.9923	0.0859	0.182

## B. Experiments

To conduct experiments, we have implemented the proposed algorithm using 100 color images in UC Berkeley photo library <sup>1</sup>. In experiment, the results are compared with the previous clustering method to assess the quality of the proposed algorithm.

Fig. 1 shows the results of experiments on 10 sample images with the number of cluster and fuzzy parameters were identified, using three clustering algorithms FCM, FCC and IT2FCC. From the result in Fig. 1, validity indexes of IT2FCC are better than FCM and FCC. Clustering method achieves the higher value of  $PC_u$  and IQI or the lower value of  $PE_u$  and MSE then the algorithm exhibits the better clustering quality.

Table I lists the results of clustering experiments on a sample image "147091.jpg" with number of clusters from 3 to 10, using three difference clustering methods FCM, FCC and IT2FCC. According to results shown in the table, the validity indexes S and CS of three considered clustering algorithms reaches minimal value at the number of clusters is 4.

Fig. 2 shows the results of clustering experiments on sample image "147091.jpg" as color images, with the number of clusters from 2 to 10, using clustering method IT2FCC, the resulting pixels in the same cluster is filled with a specified color.

<sup>1</sup>http://www.eecs.berkeley.edu/ Research/ Projects/ CS/ vision/ bsds/BSDS300/html/dataset/images.html, downloaded in 2014

# V. CONCLUSION

In this paper, Interval Type-2 Fuzzy Co-Clustering algorithm has presented as a combination fuzzy co-clustering and interval type-2 fuzzy sets. This extension is to use the fuzzifier parameters in the objective function of fuzzy co-clustering with two fuzzifiers to make a FOU. Experiment was conducted on the UC Berkeley image data sets in comparison with FCM and FCC algorithms to show advance of the proposed algorithm.

The next goal is to extend to the proposed algorithm for other application such as text classification or multi-spectral image classification.

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Fig. 2. Image segmentation results with different number of clusters

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